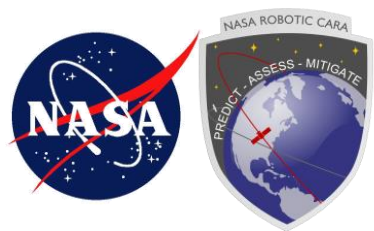




## CARA Risk Assessment Thresholds

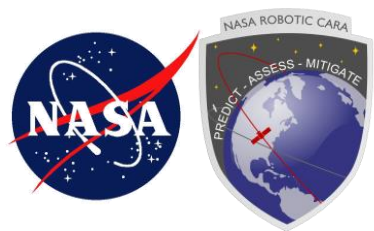
M.D. Hejduk

MAY 2016



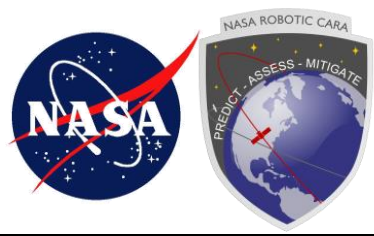
# CARA Threshold Types

- **Warning / remediation threshold (“Red” threshold)**
  - Pc level at which warnings are issued, and active remediation considered and usually executed
- **Analysis threshold (“Green to Yellow” threshold)**
  - Pc level at which analysis of event is indicated, including seeking additional information if warranted
- **Post-remediation threshold**
  - Pc level to which remediation maneuvers are sized in order to achieve event remediation and obviate any need for immediate follow-up maneuvers
- **Maneuver screening threshold**
  - Pc compliance level for routine maneuver screenings (more demanding than regular Red threshold due to additional maneuver uncertainty)

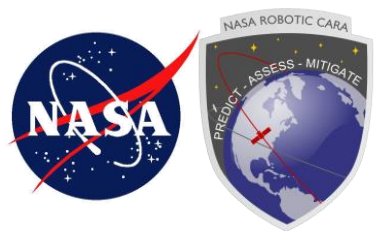


# CARA Thresholds Development Status

- **Red and Green-to-Yellow thresholds established**
  - Type 1 and Type 2 error analysis
  - Imputed workload analysis
- **Post-remediation threshold methodology in work**
  - Rule-of-thumb in place presently
  - Analysis avenues for more robust approach
- **Approach envisioned for post-remediation threshold can also be applied to maneuver screening threshold**

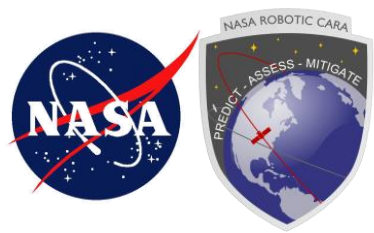


# RED AND YELLOW-GREEN THRESHOLD DETERMINATION



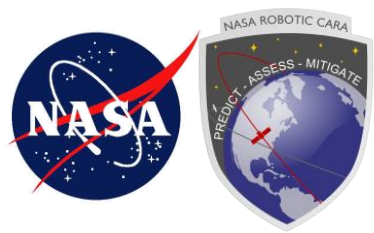
# The CARA “Worktier” System Defined

- **System for determining how much induced work a given event commanded**
  - Worktier 1: e-mail contact and follow-up with O/O
  - Worktier 2: HIE package produced and briefing delivered
  - Worktier 3: RMM planning conducted
  - Worktier 4: RMM executed
- **Worktier level a good proxy for seriousness of event**
- **Worktier level thus used as “truth” criterion to choose red and green Pc thresholds**
  - Worktier 2+ recommended as particular level to use, meaning high-risk event set defined as those with a worktier level of 2 or higher
  - Plots will, however, show performance at all four worktier levels (1+, 2+, 3+, and 4)



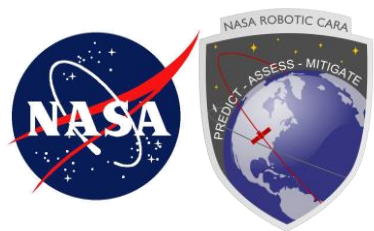
# Worktiers and Pc Threshold Circularity

- **Worktiers reasonable proxy for seriousness of event**
- **However, Pc levels presently used to establish seriousness**
  - Thus, must be careful in using historical worktier data to set Pc levels—easy to devolve into circular argumentation
- **Original examination used dataset from period before Pc thresholds established and in place**
  - Thus legitimate dataset from which to establish threshold set
- **For this reason, updates to original values no longer easily achievable through data mining**

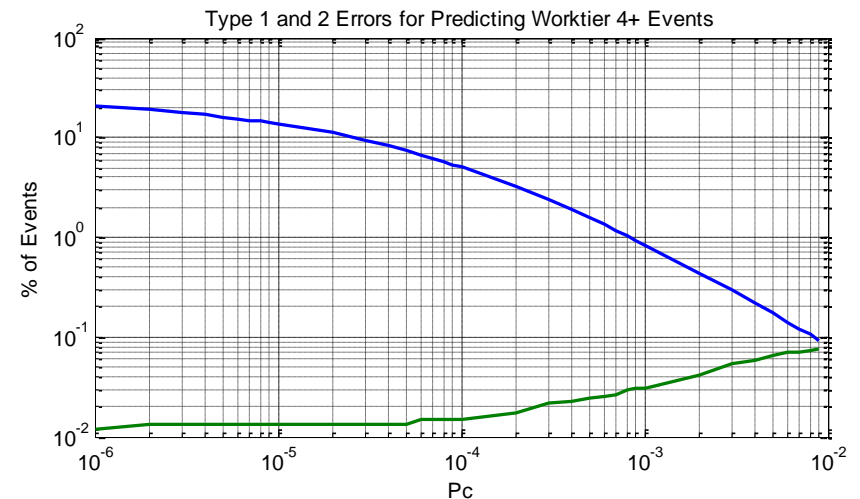
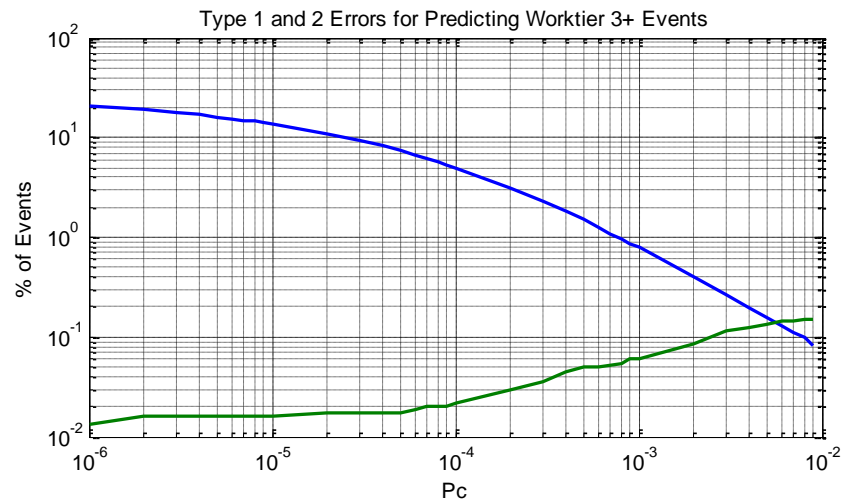
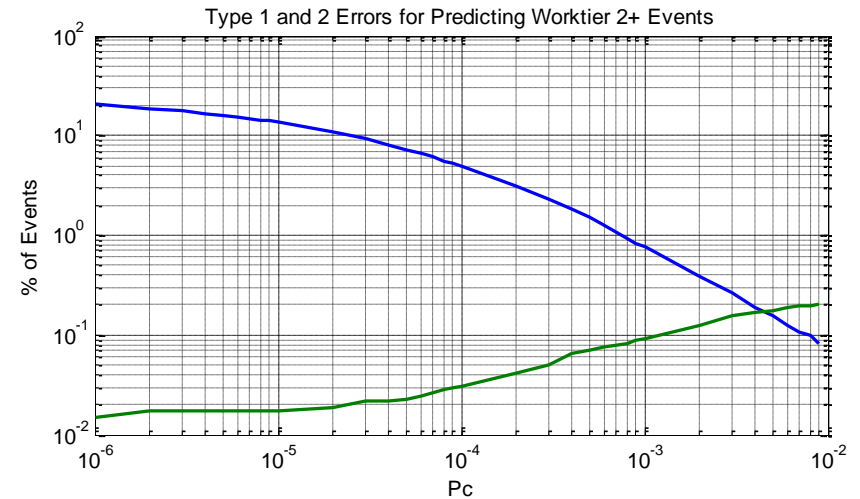
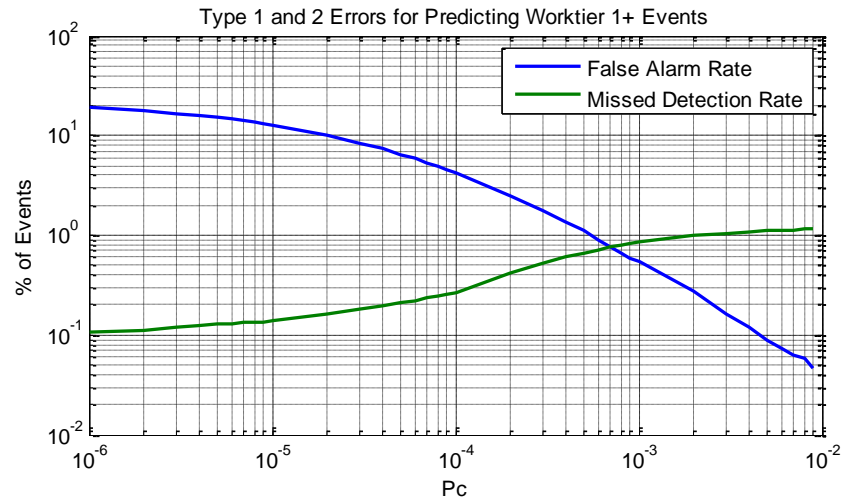


# Exploratory Analysis: Event Maximum Pc as Predictor of Worktier

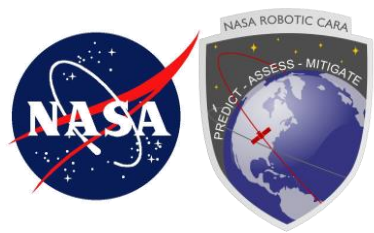
- **How good a predictor of the eventual work tier assignment is the maximum Pc during the event?**
- **Examined all events in 2011-2013**
- **One graph for each work tier**
  - Quad-chart format shows results for each cumulative worktier level
- **False alarm rate (blue line): % of cases in which the Pc indicated a serious event but the event was actually not high-risk**
  - Also called a “type 1” error, and is a nuisance factor
- **Missed detection rate (green line): % of cases in which the Pc indicated a non-high-risk situation but the event actually was high risk**
  - Also called a “type 2” error, and is the more serious error type



# Event Maximum Pc as Predictor of Worktier: Results

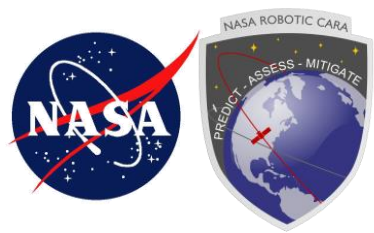






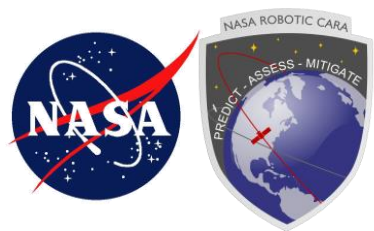
# Event Maximum Pc as Predictor of Worktier: Interpretation of Results

- **Interpretive questions center on tolerable levels for the type 1 and type 2 errors**
- **Type 2 error rates**
  - 0.01% to 0.1% for a  $1E-05$  to  $1E-03$  Pc threshold range—quite small
  - Events that are just below the red threshold can be promoted manually red and thus be processed as HIEs
- **Type 1 error rates**
  - Range from 10% to 0.5%--again, not very large and seemingly tolerable
- **Overall construct thus looks promising**

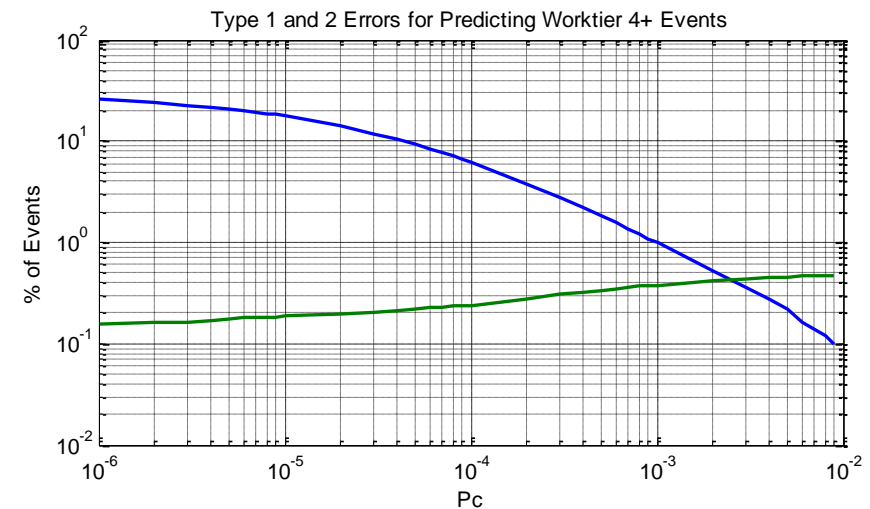
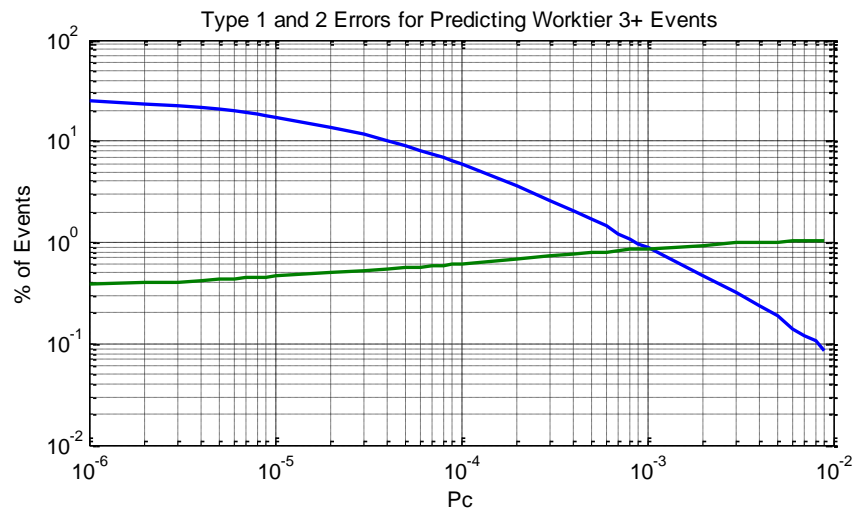
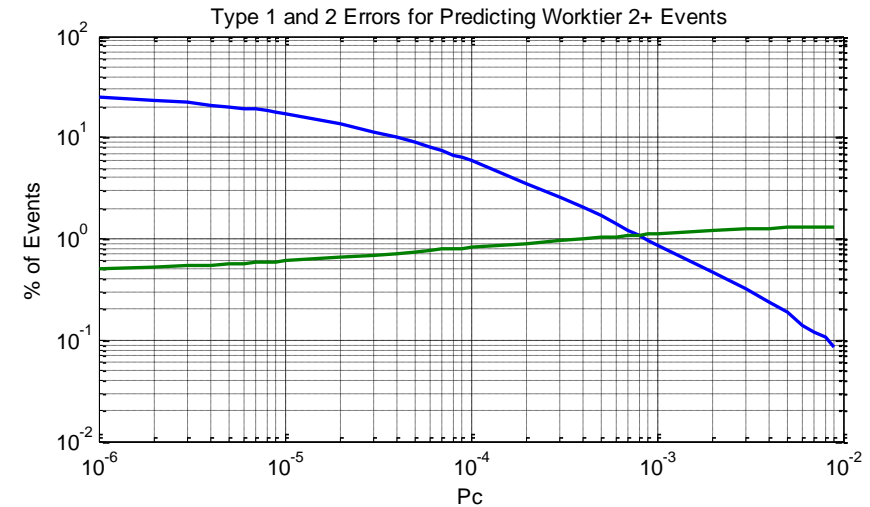
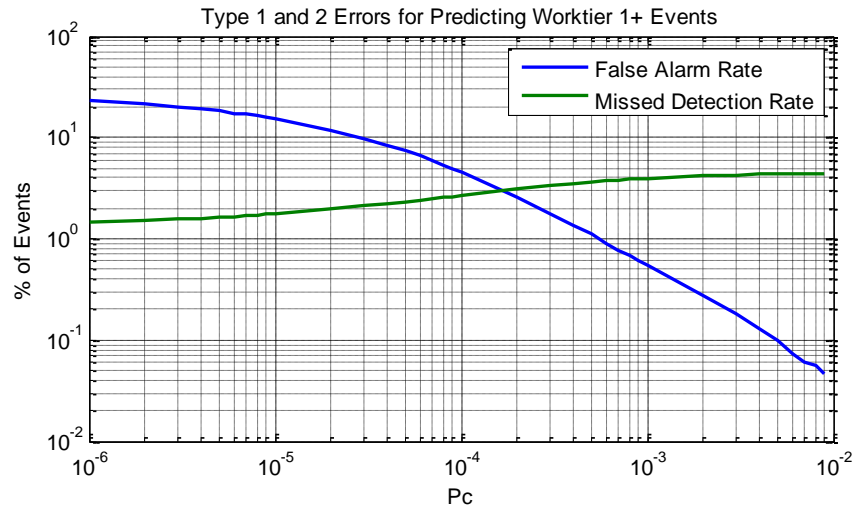


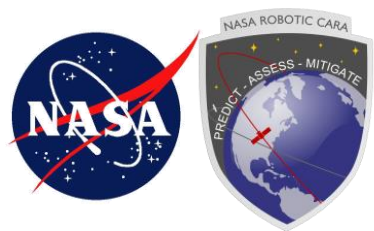
# Individual Event CDMs as Predictor of Worktier

- **A typical event consists of a chain of CDMs from 7 days to 1-2 days from TCA**
- **These usually begin with a smallish  $P_c$  value and increase to a maximum, then decrease somewhat rapidly**
- **Question now is how well each pre-max  $P_c$  value will predict the eventual worktier level of the event**
  - This is the way CONOPS will actually operate
- **Certain to perform worse than using only the max  $P_c$  value as a predictor**
  - But may still perform quite adequately for CONOPS purposes



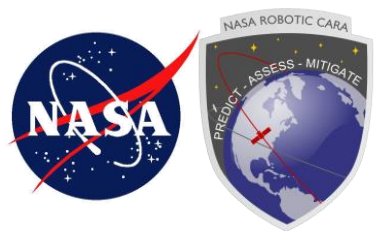
# Individual Event OCMs as Predictor of Worktier: Results





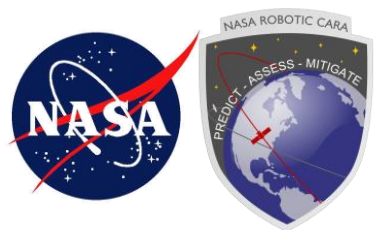
# Individual Event OCMs as Predictor of Worktier: Interpretation

- **As expected, performance is worse with this arrangement**
- **Type 2 error rates higher**
  - These are between 0.5% and 1% for the 1E-05 to 1E-03 range
  - Not blissfully low, but not particularly surprising or disturbing given what is being attempted
    - Initial relatively low  $P_c$  values in an event not readily predictive of event destiny
    - Consequence is not a missed event, only that event will not be caught as early
  - Curve relatively flat, especially below 1E-04
    - Very little marginal gain from choosing a lower threshold (e.g., 1E-05)
- **Type 1 error rates not very different from previous**
  - Not surprising, given typically lower  $P_c$  values at the beginning of events
    - Rare that early-event  $P_c$  would exceed red threshold, not be the maximum  $P_c$ , and then drop sufficiently quickly that event would not remain an HIE

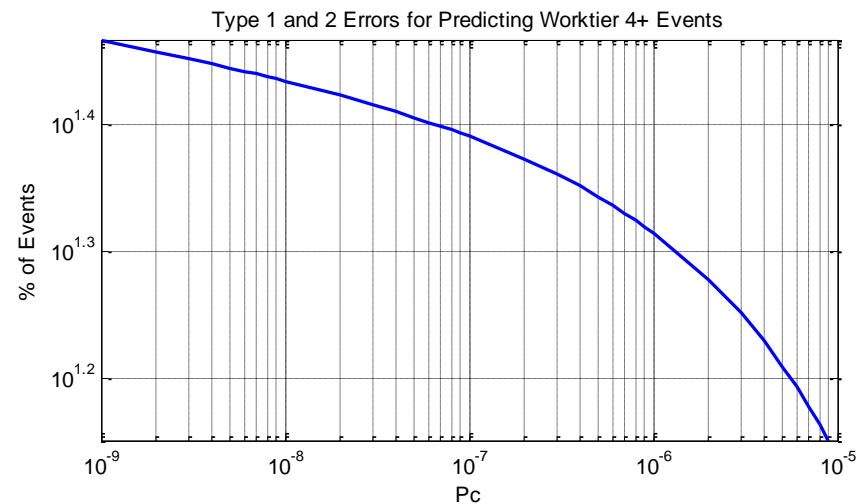
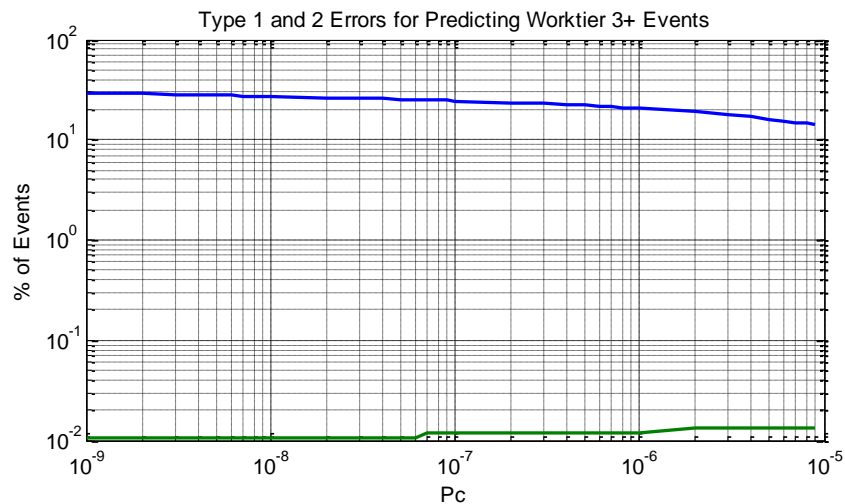
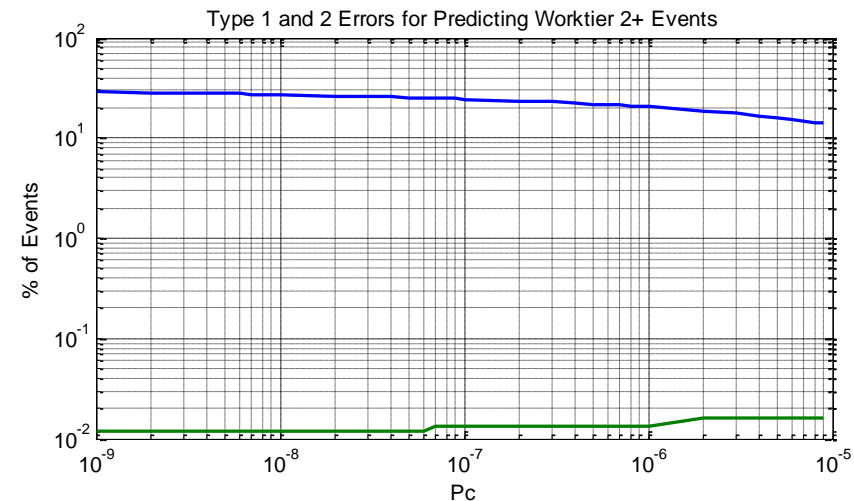
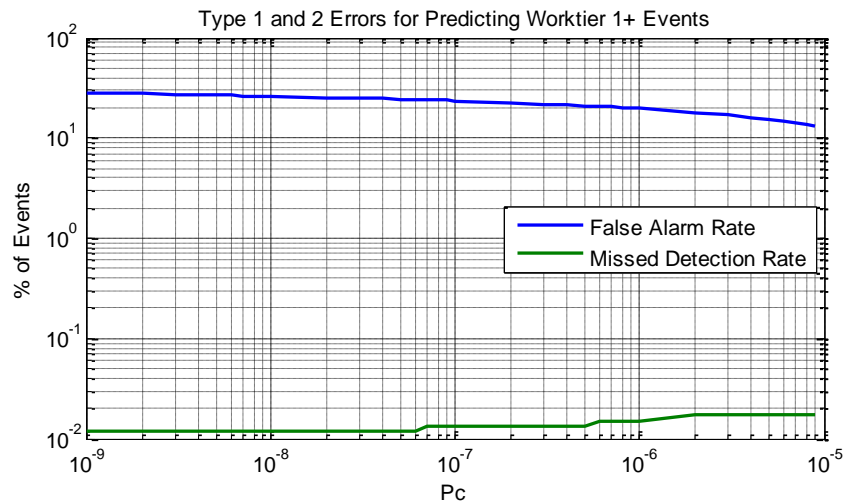


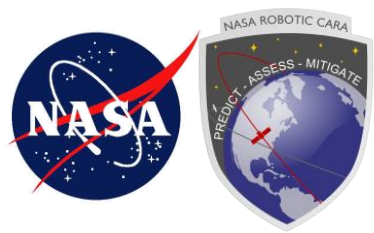
# Green-To-Yellow Threshold

- **Idea is to set a lower bound on  $P_c$  so that events with a  $P_c$  below this threshold will almost never become high-risk events**
- **Type 1 error:  $P_c$  is above this threshold but never becomes high risk**
  - Not really a false alarm, as it is expected that the great majority of non-green  $P_c$  values will remain yellow and never become high risk events
  - However, to maintain parallelism with construct used for setting red threshold, appropriate to label it a Type 1 error
- **Type 2 error:  $P_c$  is below this threshold but becomes high risk**
  - Even here, the problem is not particularly serious: events are not missed but just have their true severity discovered somewhat later
- **Investigate against all pre-max- $P_c$  OCMs in each event**



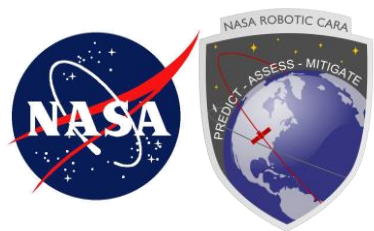
# Green Threshold Performance: Pre-max-OCMs in each Event





# Green Threshold Performance: Interpretation

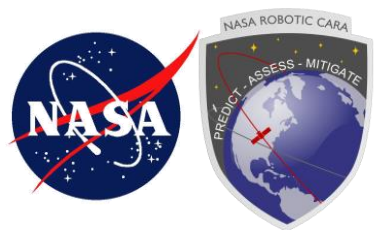
- **Type 2 error performance**
  - Stable at 0.015% for 1E-08 to 1E-06
  - Numbers quite low
- **Type 1 error performance**
  - Ranges from 30% to 20%
  - Numbers seem high, but actually have little significance
    - Essentially # of yellow events that never become red—this is expected



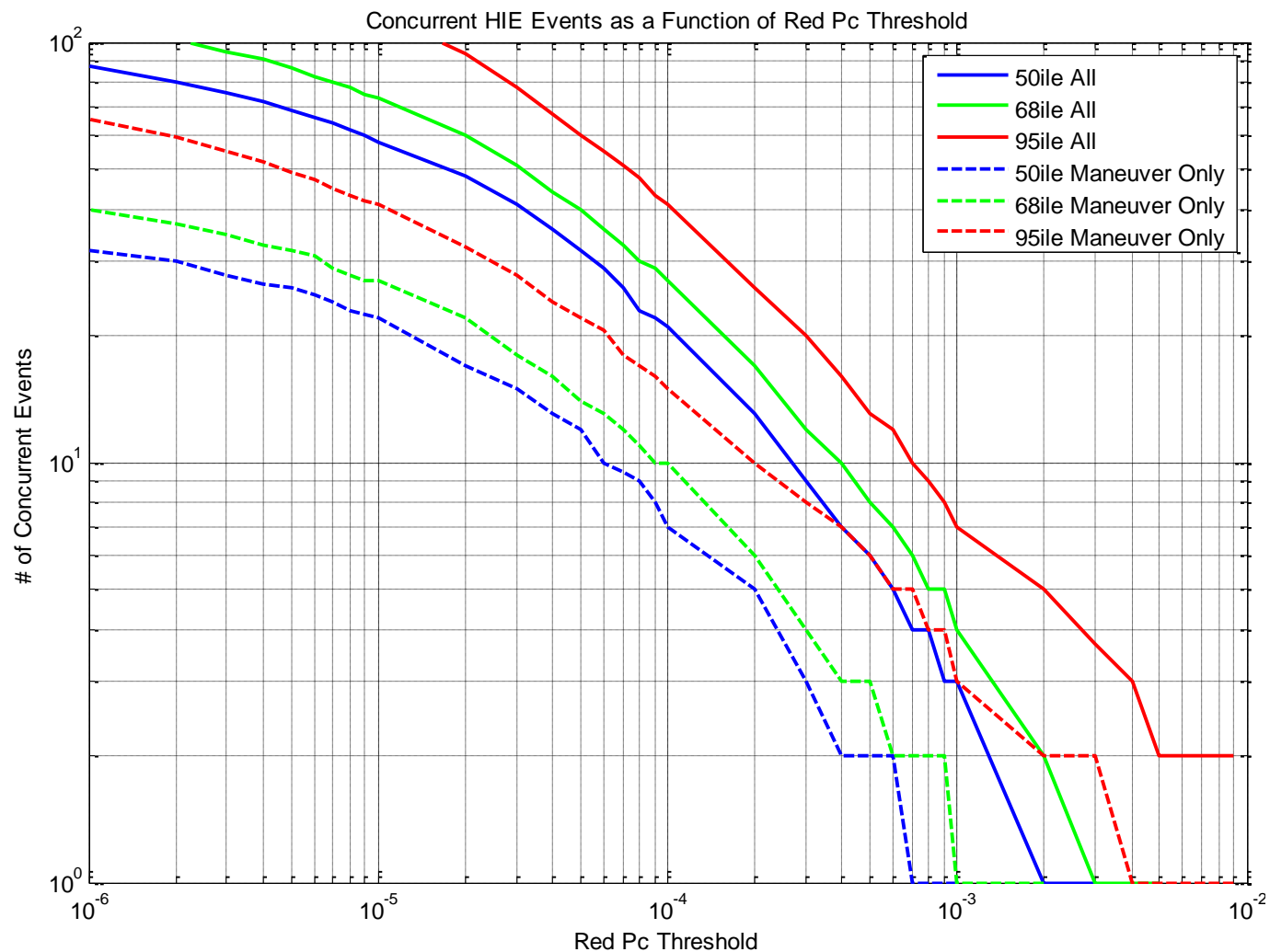
# Concurrent Events

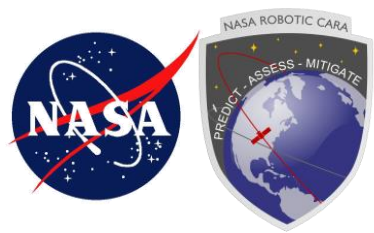
- **If an event's  $P_c$  exceeds the red threshold, it becomes an HIE**
  - Usual dynamics is for the event to remain at this level until TCA
- **Can thus determine the number of concurrent HIEs implied by a particular red threshold**
  - # of concurrent HIEs per day over the 2011-2013 period
  - Summarized by 50<sup>th</sup>, 68<sup>th</sup>, and 95<sup>th</sup> percentiles
  - Separate lines for all satellites and maneuverable satellites only
- **Graph on next slide**





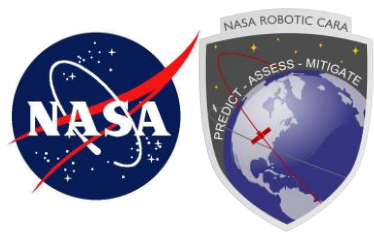
# Concurrent Events Plot





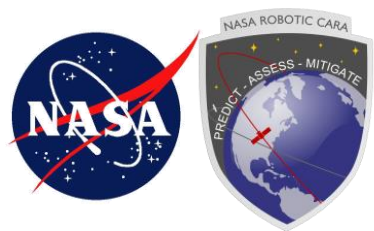
# Concurrent Events: Interpretation

- **Workload becomes problematic around  $5E-04$  with current staffing**
- **Must also consider imputed workload on missions with more frequent HIEs**

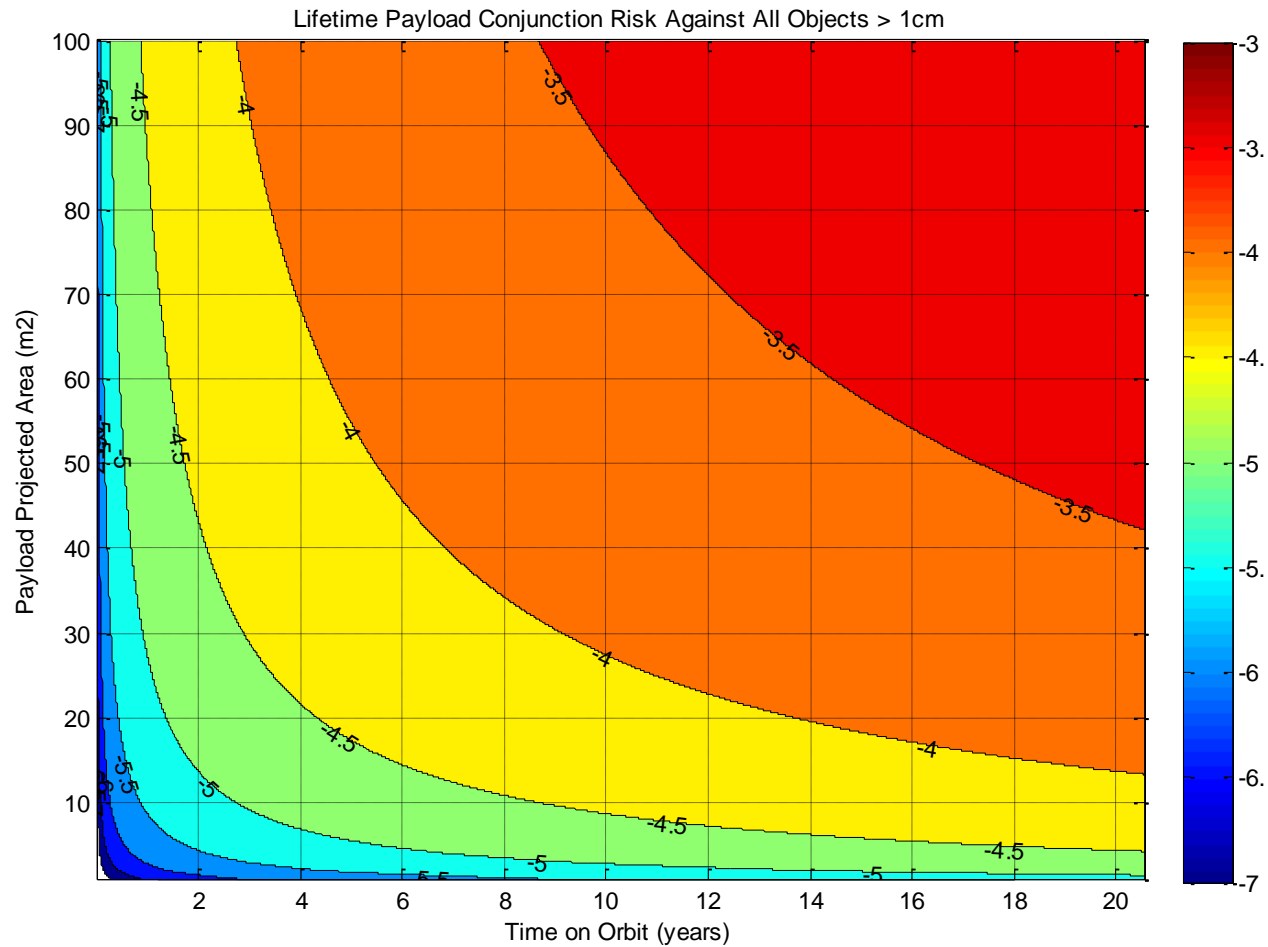


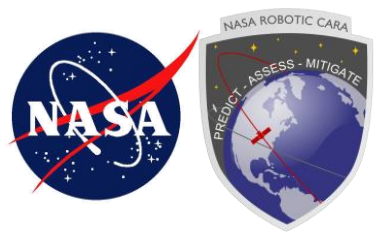
# Satellite Lifetime Conjunction Risk

- **Aerospace study developed factor for satellite lifetime conjunction risk calculation**
  - 1E-08 per 10 m<sup>2</sup> of spacecraft projected area per day
  - Based on older version of ORDEM and not orbit regime dependent, so a durable result would require re-execution of the study
  - However, factor can be used to produce results to provide orientation
- **Contour plot gives composite satellite conjunction risk as a function of spacecraft size and years on orbit**
  - Colors represent  $\log_{10}(P_c)$



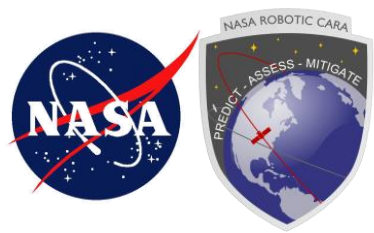
# Lifetime Conjunction Risk Contour Plot





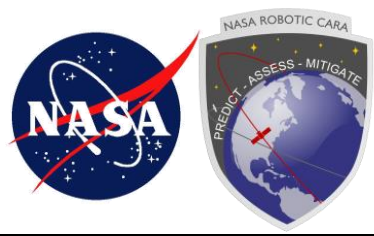
# Satellite Lifetime Conjunction Risk: Interpretation

- **Satellites with a reasonable lifetime on orbit (~10 years) and a non-trivial size ( $\sim 4\text{m}^2$ ) have a lifetime conjunction risk of  $\sim 3\text{E-04}$**
- **Does not make sense to remediate conjunctions with a risk much smaller than this**

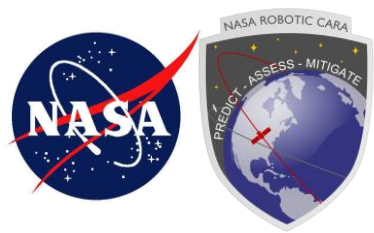


# Overall Summary

- **Analysis does not point to single value for red or green threshold**
- **However**
  - Region between  $1\text{E-}04$  and  $5\text{E-}04$  seems to be a reasonable choice for red threshold
    - Type 2 error rates OK (0.05% or so)
    - Type 1 error rates OK also (~5%)
  - Not much improvement in situation in choosing a smaller threshold
    - Type 2 error curves relatively flat
  - Workload, however, does increase substantially when smaller threshold chosen
  - Smaller thresholds begin to approach lifetime conjunction risk values, most of which is due to untrackable small debris
- **CARA  $\sim 4\text{E-}04$  choice, while not made inevitable by this analysis, is reasonably supported by it**



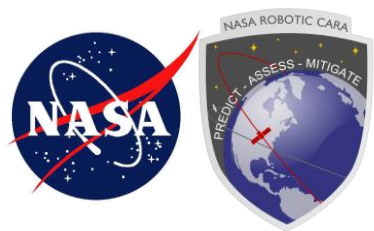
# POST-MANEUVER THRESHOLD DETERMINATIONS



# CARA Post-Remediation Threshold

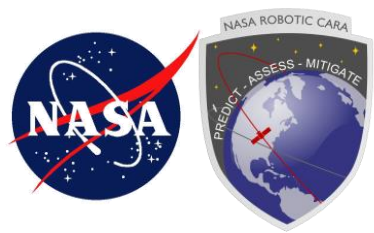
- **Current recommendation is to choose maneuver to reduce cumulative  $P_c$  to  $1E-10$** 
  - Rule of thumb that has arisen over the years
  - Intent is essentially to eliminate need for follow-up maneuver because original maneuver inadequately sized
- **Many missions now push back against this conservative value**
  - Can put missions outside of control box
  - Even if executable, can consume large amount of fuel
  - No rigorous justification at present for value
- **Sketch of expected approach to resolution to follow**





# Pc Uncertainty and Post-Maneuver Remediation

- **Pc Uncertainty construct pursued by CARA for years; briefed recently at AAS (paper 16-241)**
- **Considers all of the uncertainties in the input parameters to generate a PDF of Pc values, rather than a single value**
- **Can use to determine likelihood of obtaining a Pc of a certain value or higher at a given percentile point**
  - E.g., 5% or lower chance that the Pc will exceed  $1E-04$
- **Can incorporate into Maneuver Trade-Space functionality**
  - Function presently produces contour plot of Pc as a function of maneuver size and maneuver execution time (phasing)
  - Pc uncertainty can be used instead to give the likelihood of the post-maneuver Pc exceeding a specified threshold
    - Perhaps  $4.4E-04$  or  $1E-05$  (red and maneuver planning thresholds)
    - Graph could show likelihood of Pc exceeding  $1E-05$ ; perhaps choose 2% or less
  - Frames output in terms of likelihood of post-maneuver high risk
  - Works best if maneuver execution error incorporated into construct



# CARA Maneuver Screening Threshold

- **Same approach as for RMM sizing can be used**
- **Both canonical threshold and percentile point could be different**
- **Setting of percentile points can be informed by regular operational practice**
  - i.e., percentile point to be used when evaluating red threshold under regular conditions